# Data Sheet

# TAG201N1030

				R	Е	V	I	S	I	О	N	S		_			
No.	DATE	P A C	6 E		DESCRIPTION DS'D											CH'D	APP'D
														ED'N	No.		
DS' I	O A.Abe	Έ	E MODEL No. TITLE														
CH'	CH' D '12.0						TAG	201N	1030					Data	a She	et	
	T.Imamu	ra	DWG	NO.	3	3	4	5	6	; ;	7	8	9	10	1	1 12	SHEET
APP'	D M.Yachi		S	P	C	,	0	0	4		9	6	1	W	0	0	1/0

# Data Sheet

- 1. Scope
- 2. Parts number
- 3. Mechanical characteristics
- 4. Ratings
- 5. Electrical characteristics
- 6. Measurement circuit
- 7. Assembly recommendation
- 8. Instructions

## 1. Scope

This specification is applied to the angular rate sensor.

## 2. Parts number

# 2-1. Tamagawa Seiki parts number TAG201N1030

### 3. Mechanical characteristics

### 3-1. Dimension

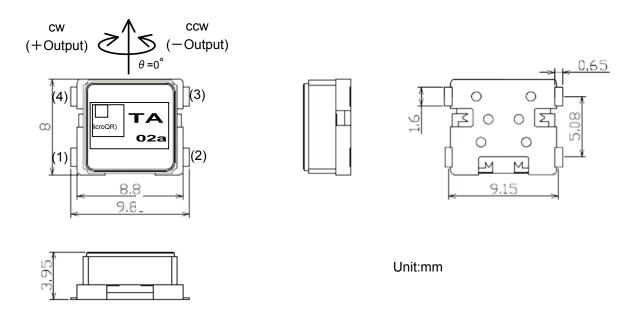


Figure-1. Dimension

## 3-2. Terminal Configurations

Table-1. Terminal Configurations

No	Terminal name	Description				
(1)	Vout	Rate sensor output				
(2)	Vcc	Power supply voltage				
(2)	TO	Temperature sensor output				
(3)	TS	(Not connected in case of nonuse)				
(4)	GND	Ground				

								ED'N No	о.		
DWG NO.	3	4	5	6	7	8	9	10	11	12	SHEET
SP	C	0	0	4	9	6	1	W	0	0	3/8

# 3-3. Marking

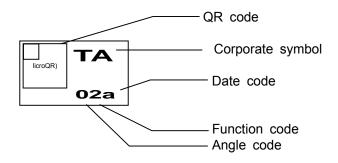


Figure-2. Marking

## 4. Ratings

# 4-1. Absolute maximum ratings

Table-2. Absolute maximum ratings

No.	Parameter	Specification	Unit	Note.
1	Supply voltage	-0.3 to +7.0	٧	
2	Operating temperature range	-40 to +85	°C	
3	Storage temperature range	-40 to +85	°C	
4	Mechanical shock	200	G	1 time to X-, Y-, Z-axis each, unpowered.

# 4-2. Operating conditions

Table-3. Operating conditions

No	Doromotor	9	Specificatio	n	Linit	Conditions
No.	Parameter	MIN	TYP	MAX	Unit	Conditions
1	Supply voltage range	4.75	5	5.25	V	
2	Measurement range	-200		200	° /sec	
3	Frequency response	-7		-2	dB	f=30Hz
4	Start up time			0.7	sec	25°C ± 2°C

								ED'N No	Э.		
DWG NO.	3	4	5	6	7	8	9	10	11	12	SHEET
SP	C	0	0	4	9	6	1	W	0	0	4/8

#### 5. Electrical characteristics

#### 5-1. Rate sensor output

The following conditions are adopted, unless otherwise specified.

① Temperature : 25°C±2°C

② Vcc:5V±0.01V

Table-4. Electrical characteristics

No.	Doromotor	9	Specification	า	Unit	Conditions
INO.	Parameter	MIN	TYP	MAX	Unit	Conditions
1	Supply current			6	mA	
2	Maximum output voltage	Vcc - 0.3			V	
3	Minimum output voltage			0.3	V	
4	Nominal bias	2.4	2.5	2.6	V	
4	NOMINAL DIAS	2.35	2.5	2.65	V	Ta= -40 to +85°C
5	Bias drift after power on	-15		15	mV	0.7sec to 15minutes
6	Scale factor	9.5	10.0	10.5	mV/°/sec	
0	Scale factor	9.0	10.0	11.0	mV/°/sec	Ta= -40 to +85°C
7	Scale factor symmetry	-1.0		1.0	%	
8	Linearity	-0.5		0.5	%Fs	
9	Cross axis sensitivity	-5		5	%	Ta= -40 to +85°C
10	Output noise			5	mVpp/5s	Ta= -40 to +85°C
11	Ratiometric error for bias	-20	0	20	%	Start-up from 0.7s~ Vcc:4.75V to 5.25V
12	Ratiometric error for scale factor	-20	0	20	%	Start-up from 0.7s~ Vcc:4.75V to 5.25V

Table-5. Electrical characteristics (Variation with temperature)

No	Doromotor	5	Specification	n	Linit	Conditions
No.	Parameter	MIN	TYP	MAX	Unit	Conditions
13	Bias variation with temperature (Max-Min)			8	° /sec	Ta= -40 to +85°C
14	Bias variation with	-6		6	mV/2.5°C	Ta= -40 to +85°C
14	temperature	-13		13	mV/7.5°C	Ta= -40 to +85°C
15	Scale factor variation with temperature	-3.0		3.0	%	Ta= -40 to +85°C

# Note:

- $\cdot$  Bias variation with temperature assumes it the measurement at case of the temperature rise.
- ·Load impedance of 100k  $\Omega$  and 0.1  $\mu$  F to be connected between terminals Vout and GND in parallel.

									ED'N No	о.		
DWG 1	DWG NO.		4	5	6	7	8	9	10	11	12	SHEET
S	P	C	0	0	4	9	6	1	W	0	0	5/8

#### 5-2. Temperature sensor output

Table-6. Temperature sensor output

No.	Doromotor	9	Specification	า	Linit	Conditions
INO.	Parameter	MIN	TYP	MAX	Unit	Conditions
1	Temperature sensor output	1.33	1.4	1.47	V	Ta=25°C
2	Temperature sensor scale factor	-3.6	-3.8	-4.0	mV/°C	Ta= -40 to +85°C

#### Note:

• Temperature sensor output is not ratiometric on supply voltage.

#### <Definition of the term>

- Measurement range: Angular rate measuring range for guarantee of performance
- Maximum output voltage ; Output voltage at input angular rate of +500 ° /sec
- Minimum output voltage ; Output voltage at input angular rate of -500  $^{\circ}$  /sec
- Nominal bias ; Output voltage at input angular rate of 0 ° /sec
- Bias drift after power on ; Maximum value of drift of bias during turned on state of applying electric power supply, where noise under 10mV is excluded.
- Scale factor; Ratio of the output voltage versus the rotating angular rate being applied.
- Scale factor symmetry; A typical value of asymmetry of sensitivity defined as a ratio of the sensitivity applying plus value of a specified input voltage to minus value of a specified input voltage.
- Linearity ; ((Sνω-Sνmax)/(Sνmax×ωmax))×ω×100 Linearity of CW direction,

in the same as CCW direction.

 $Sv\omega$ : Scale factor when angular rate is  $\omega$ 

ωmax; Maximum angular rate

Svmax; Scale factor at  $\omega_{max}$ 

- (9) Cross axis sensitivity: Maximum value of sensitivity of cross axis
- ① Output noise; Output noise at stable state operation.
- 1 Ratiometric error for bias ; Maximum value of error of bias applying voltage fluctuation caused by operating instability of applying electric power supply.

 $V0(Vcc)/V0(5V)-(Vcc/5)/(Vcc/5-1) \times 100 (\%)$ 

- Ratiometric error for scale factor; Maximum value of error of sensitivity applying voltage fluctuation caused by operating instability of applying electric power supply.  $Sv(Vcc)/Sv(5V)-(Vcc/5)/(Vcc/5-1) \times 100 (%)$
- Bias variation with temperature: Maximum value of standard bias under a specified variation in temperature.
- Scale factor variation with temperature; Minimum and maximum value of standard s ensitivity under a specified variation in temperature

								ED'N No	о.		
DWG NO	. 3	4	5	6	7	8	9	10	11	12	SHEET
	P C	0	0	4	9	6	1	$\mid \mathbf{W} \mid$	0	0	6/8

#### 6. Measurement circuit

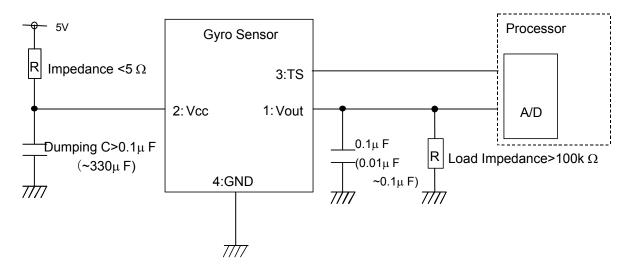


Figure-3. Measurement circuit

#### Note:

- To decrease the ripple voltage of the supply voltage, recommend to use the capacitor of large capacitance in order to avoid such phenomena.
- High impedance of Vout and TS terminal is needed. (Please attach the load resistance more than  $100k\Omega$  if needed.)

#### 7. Assembly recommendation

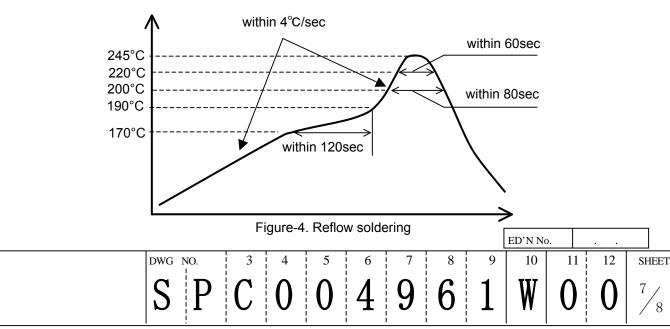
7-1. Assembly recommendation

7-1-1. Soldering temperature profile of reflow

(1)170 $\sim$ 190°C : within 120sec (2)200°C or higher : within 80sec (3)220°C or higher : within 60sec

(4)Peak temperature : 245°C, within 40sec

Where used solder is Sn-3Ag-0.5Cu [Measurement point: Board surface]



#### 7-1-2. Soldering temperature profile of iron

At 1 lead Temperature: Lower than 300°C Time: within 3s

#### 7-2. Recommended footprint

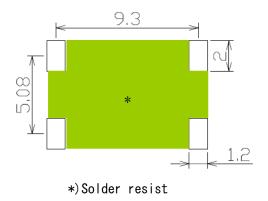


Figure-5. Recommended footprint

#### 8. Instructions

- 8-1. This product uses Bi-CMOS IC inside. Against static electricity discharge is needed.
- 8-2. Connected correctly is needed.
- 8-3. Reflow soldering applied only once.
- 8-4. Products shown in this catalog are designed and manufactured with an object for general use, such as the ordinary industrial use, general office work, and personal/home use. They are not designed and manufactured for the use which requires high reliability (under-water stations and space satellites), and the use which requires high safety and if the safety is not secures, it has serious influence socially and directly onto life and body (nuclear reaction control in nuclear facilities, airplane automatic flight control, air traffic control, traffic control in a mass transportation system, medical equipment for life maintenance, and missile launch control in an arms system). Therefore those who are considering use of our products in these fields are advised to consult our Sales Department in advance. We cannot take responsibility for damages resulting from the failure in the consultation.

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In case our product in this catalog corresponds to a cargo or technology regulated based on "a foreign exchange and a foreign trade law", the permission based on the law is required in exporting the product.

								ED'N No	о.		
DWG :	NO. 3	4	5	6	7	8	9	10	11	12	SHEET
S	PC	0	0	4	9	6	1	W	0	0	8/8